



Jordan Boyd-Graber University of Colorado Boulder LECTURE 7

Slides adapted from Tom Mitchell, Eric Xing, and Lauren Hannah

Roadmap

- Classification: machines labeling data for us
- Previously: naïve Bayes and logistic regression
- This time: SVMs
 - o (another) example of linear classifier
 - State-of-the-art classification
 - Good theoretical properties

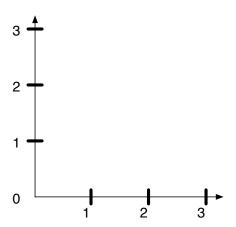
Thinking Geometrically

- Suppose you have two classes: vacations and sports
- Suppose you have four documents

• What does this look like in vector space?

Put the documents in vector space

Travel



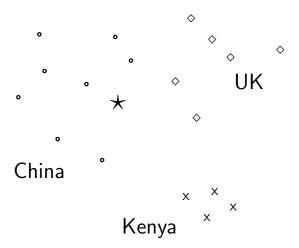
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Vector space representation of documents

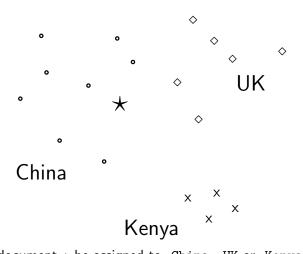
- Each document is a vector, one component for each term.
- Terms are axes.
- High dimensionality: 10,000s of dimensions and more
- How can we do classification in this space?

Vector space classification

- As before, the training set is a set of documents, each labeled with its class.
- In vector space classification, this set corresponds to a labeled set of points or vectors in the vector space.
- Premise 1: Documents in the same class form a contiguous region.
- Premise 2: Documents from different classes don't overlap.
- We define lines, surfaces, hypersurfaces to divide regions.

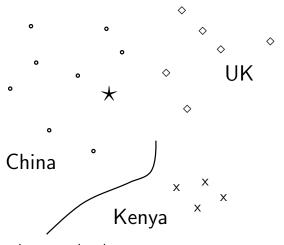


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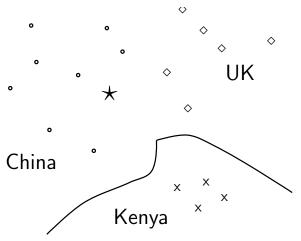
Should the document \star be assigned to China, UK or Kenya?

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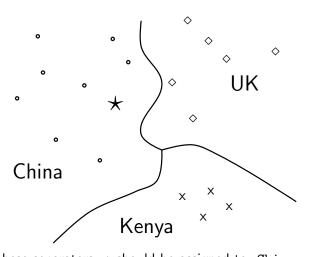
Find separators between the classes

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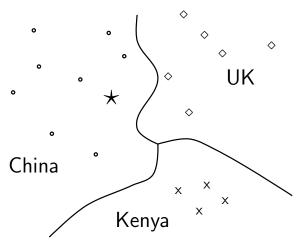
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Based on these separators: ★ should be assigned to China

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How do we find separators that do a good job at classifying new documents like \star ? – Main topic of today

Plan

Linear Classifiers

Support Vector Machines

Formulation

Theoretical Guarantees

Recap

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Linear classifiers

- Definition:
 - A linear classifier computes a linear combination or weighted sum $\sum_i \beta_i x_i$ of the feature values.
 - Classification decision: $\sum_i \beta_i x_i > \beta_0$? (β_0 is our bias)
 - ... where β_0 (the threshold) is a parameter.
- We call this the separator or decision boundary.
- We find the separator based on training set.
- Methods for finding separator: logistic regression, naïve Bayes, linear SVM
- Assumption: The classes are linearly separable.

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- Assumption: The classes are linearly separable.
- Before, we just talked about equations. What's the geometric intuition?



A linear classifier in 1D is a point x described by the equation $\beta_1 x_1 = \beta_0$

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• $x = \beta_0/\beta_1$

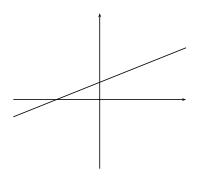


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- $x = \beta_0/\beta_1$
- Points (x_1) with $\beta_1 x_1 \ge \beta_0$ are in the class c.

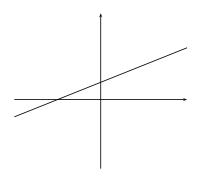
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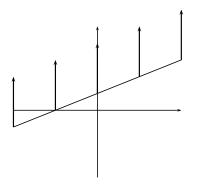
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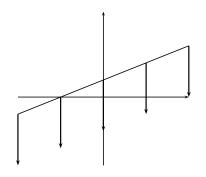
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- Example for a 2D linear classifier

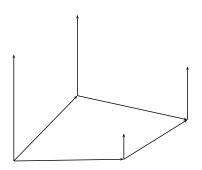


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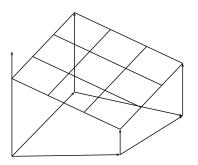
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 A linear classifier in 3D is a plane described by the equation

$$\beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 = \beta_0$$

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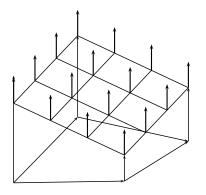


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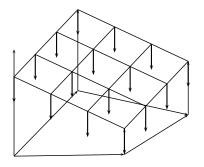
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Example for a 3D linear classifier



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- Example for a 3D linear classifier
- Points $(x_1 x_2 x_3)$ with $\beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 > \beta_0$ are in the class c.
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Naive Bayes and Logistic Regression as linear classifiers

Multinomial Naive Bayes is a linear classifier (in log space) defined by:

$$\sum_{i=1}^{M} \beta_i x_i = \beta_0$$

where $\beta_i = \log[\hat{P}(t_i|\bar{c})/\hat{P}(t_i|\bar{c})]$, $x_i =$ number of occurrences of t_i in d, and $\beta_0 = -\log[\hat{P}(c)/\hat{P}(\bar{c})]$. Here, the index i, $1 \le i \le M$, refers to terms of the vocabulary.

Logistic regression is the same (we only put it into the logistic function to turn it into a probability).

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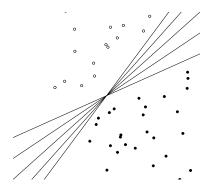
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Takeway

Naïve Bayes, logistic regression and SVM are all linear methods. They choose their hyperplanes based on different objectives: joint likelihood (NB), conditional likelihood (LR), and the margin (SVM).

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Which hyperplane?



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Which hyperplane?

- For linearly separable training sets: there are infinitely many separating hyperplanes.
- They all separate the training set perfectly . . .
- ...but they behave differently on test data.
- Error rates on new data are low for some, high for others.
- How do we find a low-error separator?

Plan

Linear Classifiers

Support Vector Machines

Formulation

Theoretical Guarantees

Recap

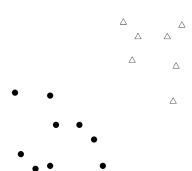
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- Machine-learning research in the last two decades has improved classifier effectiveness.
- New generation of state-of-the-art classifiers: support vector machines (SVMs), boosted decision trees, regularized logistic regression, neural networks, and random forests
- Applications to IR problems, particularly text classification

SVMs: A kind of large-margin classifier

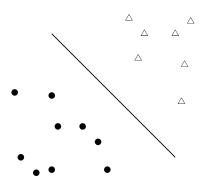
Vector space based machine-learning method aiming to find a decision boundary between two classes that is maximally far from any point in the training data (possibly discounting some points as outliers or noise)

• 2-class training data



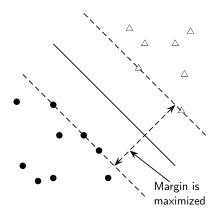
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- 2-class training data
- decision boundary → linear separator



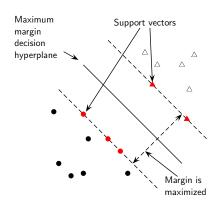
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- 2-class training data
- decision boundary → linear separator
- criterion: being maximally far away from any data point → determines classifier margin



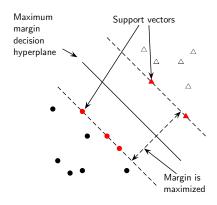
Support Vector Machines

- 2-class training data
- decision boundary → linear separator
- criterion: being maximally far away from any data point → determines classifier margin
- linear separator position defined by support vectors



Why maximize the margin?

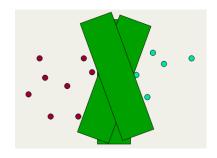
- Points near decision surface → uncertain classification decisions
- A classifier with a large margin is always confident
- Gives classification safety margin (measurement or variation)



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Why maximize the margin?

- SVM classifier: large margin around decision boundary
- compare to decision hyperplane: place fat separator between classes
 - unique solution
- decreased memory capacity
- increased ability to correctly generalize to test data



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Equation

Equation of a hyperplane

$$\vec{w} \cdot x_i + b = 0 \tag{1}$$

Distance of a point to hyperplane

$$\frac{|\vec{w} \cdot x_i + b|}{||\vec{w}||} \tag{2}$$

The margin ρ is given by

$$\rho \equiv \min_{(x,y)\in S} \frac{|\vec{w} \cdot x_i + b|}{||\vec{w}||} = \frac{1}{||\vec{w}||}$$
(3)

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• This is because for any point on the marginal hyperplane, $\vec{w} \cdot x + b = \pm 1$

Optimization Problem

We want to find a weight vector \vec{w} and bias b that optimize

$$\min_{\vec{w},b} \frac{1}{2} ||w||^2 \tag{4}$$

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subject to $y_i(\vec{w} \cdot x_i + b) \ge 1$, $\forall i \in [1, m]$.

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Next week: algorithm

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Three Proofs that Suggest SVMs will Work

- Leave-one-out error
- VC Dimension
- Margin analysis

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Leave One Out Error (sketch)

Leave one out error is the error by using one point as your test set (averaged over all such points).

$$\hat{R}_{LOO} = \frac{1}{m} \sum_{i=1}^{m} \mathbb{1} \left[h_{s - \{x_i\}} \neq y_i \right]$$
 (5)

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Leave One Out Error (sketch)

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$$\hat{R}_{LOO} = \frac{1}{m} \sum_{i=1}^{m} \mathbb{1} \left[h_{s - \{x_i\}} \neq y_i \right]$$
 (5)

This serves as an unbiased estimate of generalization error for samples of size m-1:

$$\mathbb{E}_{S \sim D^m} \left[\hat{R}_{LOO} \right] = \mathbb{E}_{S' \sim D^{m-1}} \left[R(h_{S'}) \right]$$
 (6)

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Leave One Out Error (sketch)

Let h_S be the hypothesis returned by SVMs for a separable sample S, and let $N_{SV}(S)$ be the number of support vectors that define h_S .

$$\mathbb{E}_{S \sim D^m} \left[R(h_s) \right] \le \mathbb{E}_{S \sim D^{m+1}} \left[\frac{N_{SV}(S)}{m+1} \right] \tag{7}$$

Consider the held out error for x_i .

- If x_i was not a support vector, the answer doesn't change.
- If x; was a support vector, it could change the answer; this is when we can have an error.

There are $N_{SV}(S)$ support vectors and thus $N_{SV}(S)$ possible errors.

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VC Dimension Argument

Remember discussion VC dimension for d-dimensional hyperplanes? That applies here:

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{2(d+1)\log\frac{\epsilon}{d+1}}{m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}$$
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But this is useless when d is large (e.g. for text).

Margin Theory

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To see where SVMs really shine, consider the margin loss ρ :

$$\Phi_{\rho}(x) = \begin{cases} 0 & \text{if } \rho \le x \\ 1 - \frac{x}{\rho} & \text{if } 0 \le x \le \rho \\ 1 & \text{if } x \le 0 \end{cases}$$
 (9)

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The fraction of the points in the training sample S that have been misclassified or classified with confidence less than ρ .

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Generalization

For linear classifiers $H = \{x \mapsto w \cdot x : ||w|| \le \Lambda\}$ and data $X \in \{x : ||x|| \le r\}$. Fix $\rho > 0$ then with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \le \hat{R}_{\rho}(h) + 2\sqrt{\frac{r^2\Lambda^2}{\rho^2 m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}$$
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- Data-dependent: must be separable with a margin
- Fortunately, many data do have good margin properties
- SVMs can find good classifiers in those instances

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When building a text classifier, first question: how much training data is there currently available?

- None?
- Very little?
- A fair amount?
- A huge amount

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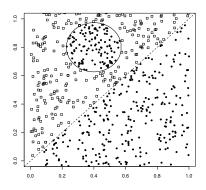
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When building a text classifier, first question: **how much training** data is there currently available?

- None? Hand write rules or use active learning
- Very little? Naïve Bayes
- A fair amount? SVM
- A huge amount Doesn't matter, use whatever works

SVM extensions: What's next

- Finding solutions
- Slack variables: not perfect line
- Kernels: different geometries



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